

Changing NMEA2000 instances

1. Introduction

Instances are used in an NMEA2000 network to identify multiple similar products connected on the same network.

As an example, take a system with two battery monitors (one for the main battery bank, and another for the hydraulic-thruster bank) and also a Quattro inverter/charger. All three of those devices will send their battery voltage measurements out on the canbus.

For the displays to show these values at the right place, they need to know which voltage belongs to what battery.

How can I change the instances?

This document describes three options:

1. Use [Actisense](#) software & hardware. Can change both the device- and data-instances
2. Use [Maretron](#) software & hardware.
3. From the [commandline](#) of a [GX device](#). Note that this is a software developer trick. Not for any day use.

Device instance vs the data instances

There are two types of instances: device instances and data instances. And depending on the make and model of the displays being used (Garmin, Maretron, Raymarine, etcetera), you need to change one of them or both.

Both the device instance and the data instance of a product can easily be changed with both Maretron N2Kview as well as and Actisense PC software.

Required hardware

Changing the device instance requires an usb-canbus adapter to link the CAN-bus network to your computer:

- For Actisense, see the [Actisense NGT-1](#)
- For Maretron, see their [USB100](#)

Related information

For more detailed information, see also the FAQ in our [Data communication whitepaper](#).

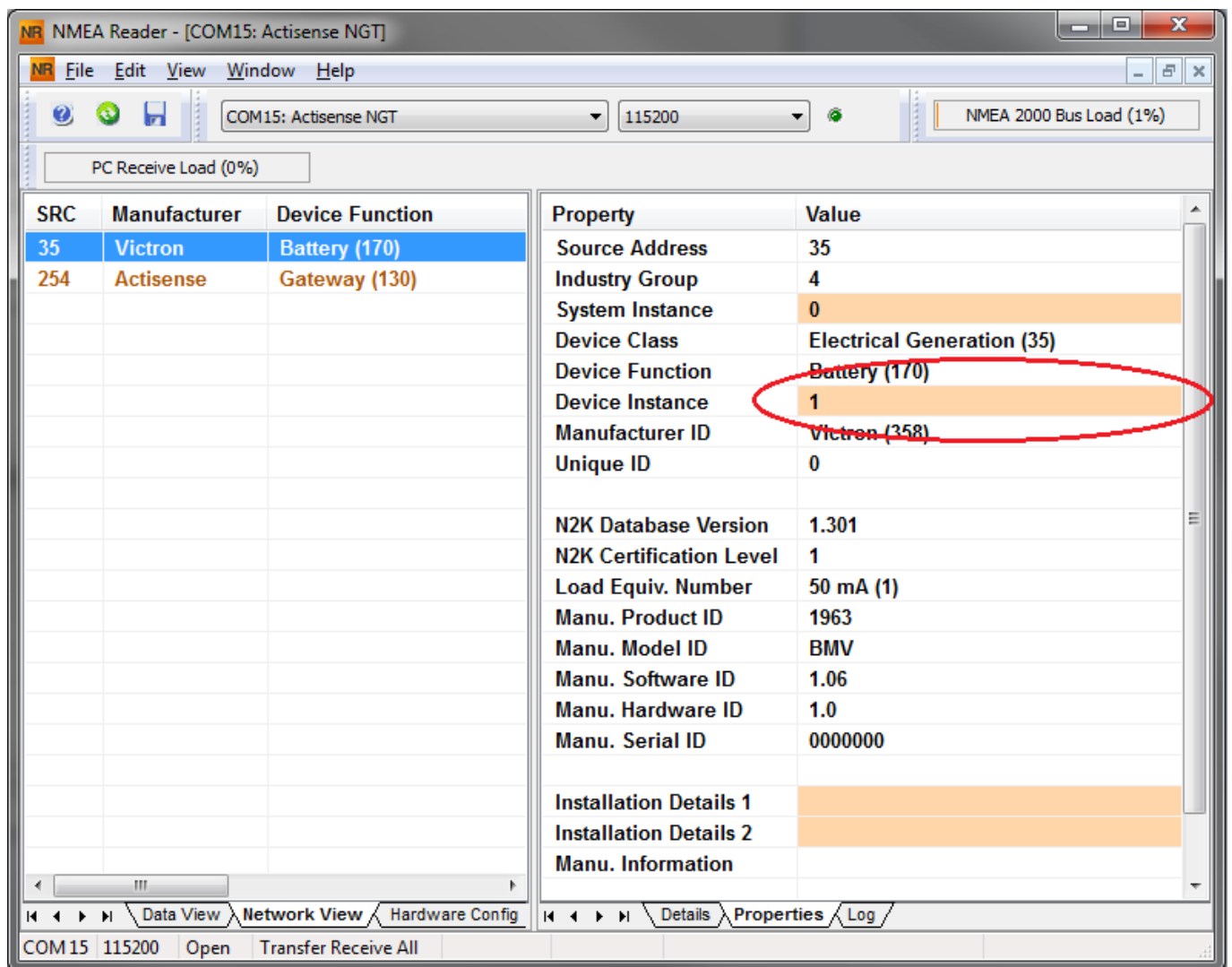
And the main [NMEA2000 integration guide](#).

2. Changing the device instance with Actisense

Note: make sure to use a recent Actisense driver. Otherwise the instance might not 'stick'.

Changing a device instance:

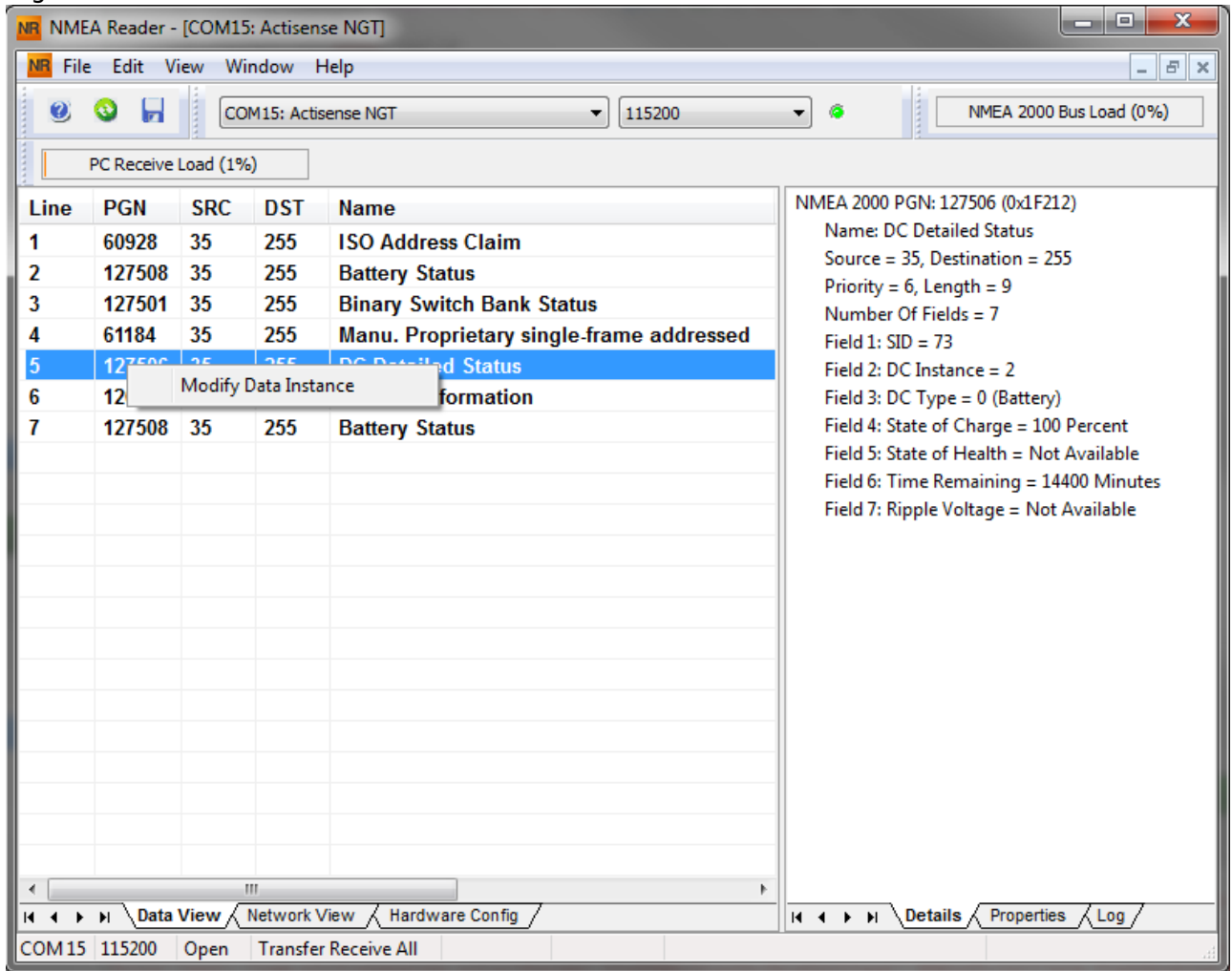
1. Open Actisense NMEA Reader
2. Select the network view (tab selection is at the bottom left)
3. Select the product whose device instance you want to change
4. Select the properties tab at the bottom right and change the device instance



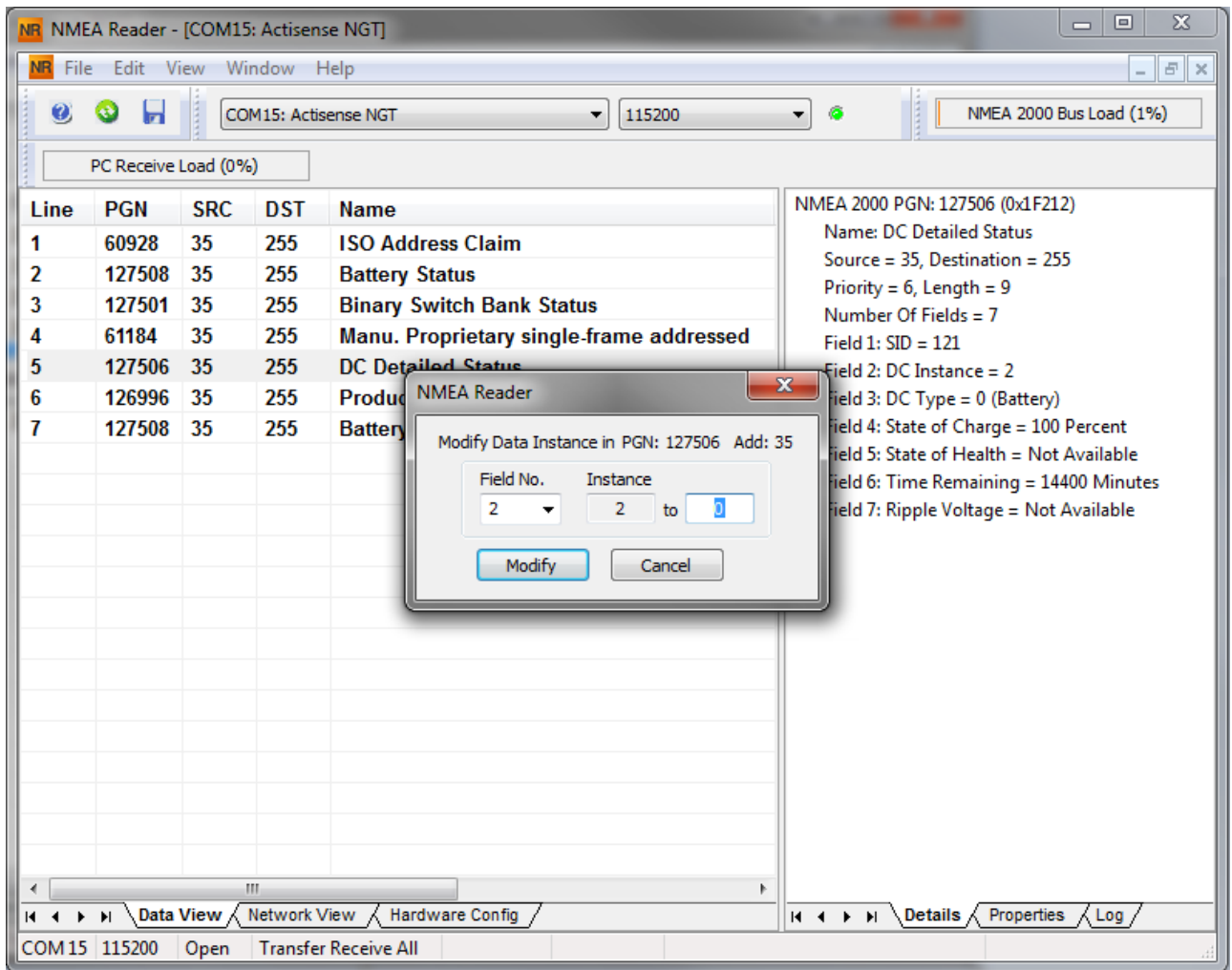
3. Changing a data instance with Actisense

Changing a data instance:

1. Open Actisense NMEA Reader
2. Select data view (tab selection is at the bottom left)
3. Right click the PGN:



4. And change the value:



Notes for BMVs, Lynx Shunt and the Lynx Ion + Shunt:

- The Battery Instance and the DC Detailed instance are the same value. Changing one of them, will also change the other one.
- Since the BMV sends out two voltages, the main voltage and the aux- or starter-voltage, it comes preconfigured with two battery instances: 0 and 1. When you want to change that to 1 and 2, change the 1 into 2 first, and then the 0 into 1, as they cannot be the same.

4. Changing Instance Using Maretron N2KAnalyzer

Maretron understands that it is sometimes difficult to know whether a particular product uses device instance or if it uses data instance to uniquely identify itself on an NMEA 2000 network. For this reason, Maretron uses a term called “Unique Instance” where the N2KAnalyzer software tool automatically determines if a particular device uses device or data instances.

Open N2KAnalyzer and make sure that the “Unique Instance” column is turned on (i.e. checked) using the Setup>Columns menu item.

Expand	Label	Mfg Model ID	Mfg Model Version	Mfg Serial Number	Unique Instance	Current Software	Available Software	Installation Description #1	Device Instance	NMEA 2000 Version	NMEA 2000 Certification Level	LET
23	DSM250 Viewing...	HT200	44-162-1-02...	11002103	2	4.000.4.001	-	Sea water temp	2	1.300	B	1
2F	AC08	AC08	Rev D	327681	64	1.11	-	AC Panel Load Sh...	64	1.200	B	2
1C	Carling Technologies	DC16	Rev F	131120	32	1.5	-	DC breakers 16x30...	32	1.200	B	1
11	Floscan Instrument Co., I...				1	V01.0.1	-		1	1.200	A	7
BA	Garmin	GPS17v...	1.00	3431140...	3	2.40	-		3	1.210	B	3
0B	Lowrance Electronics	EP-DDS	1.0.0	316	5	1.0.0 S03653	-		5	0.001	B	1
29	Maretron	VDR100	1.0	1760015	1	2.0.0.4	3.0.3.1	Connected Aft Bus...	1	2.000	A	4
CA	Maretron	DSM250	1.0	1300176	1	1.4.17.5	1.6.6.3	Deck Display	1	2.000	A	13
BF	Maretron	ACM100	1.0	1389904	0	1.0.8.2	1.0.9.2	Main A/C Bus A	0	1.301	A	1
A0	Maretron	J2K100	1.0	1241404	0	1.0.13.2	1.2.1.1	ICE Maker	0	1.301	A	3
9C	Maretron	SSC200	2.0	1120707	0	5.0.3	5.0.4.1	Primary Heading Sens...	0	1.210	A	3
30	Maretron	GPS100	1.1	1140232	2	1.6.130	2.3.0.1	Backup 1	2	1.210	A	3
7C	Maretron	TLM100	1.0	1500082	0	1.1.6	1.1.8.3	Sterboard Water	0	1.301	B	2
74	Maretron	TLM150	1.0	1529901	0	1.1.6	1.1.8.3	Tender Gasoline Tan...	0	1.301	B	2
86	Maretron	WSO100	2.0	1201734		2.0.13	2.0.13	Wind Sensor	0	1.210	A	3
72	Maretron	DST110	D235-S1-TS-...	*	0	1.003.1.022	-	Port Sounder	0	1.300	B	4
71	Maretron	ALM100	1.0	1469902	5	1.0.6	1.0.6	Engine Room	6	1.301	A	2
2D	Maretron	GPS200	2.0	15266	0	3.5	3.7.1.1	Primary GPS Ante...	0	1.301	A	3
CF	Maretron	DCM100	1.0	1400046	1	1.0.4	1.0.5.2	N2Kpower	2	1.210	A	1
73	Maretron	TLM200	1.0	1540111	2	1.1.6	1.1.8.3	Day Tank	0	1.301	B	2
0A	Maretron	USB100	1.0	1160258	1	1.8.5b1	1.8.6.2	Connected to Hel...	1	1.210	A	3
CC	Maretron	TMP100	1.0	1480009		1.1.1	1.1.2.7	Cabin Temperatures	0	1.210	A	1
CE	Maretron	TMP100	1.0	1489901		1.1.1	1.1.2.7	Engine room Rear...	0	1.210	A	1
1A	Maretron	ALM100	1.0	1460041	0	1.0.6	1.0.6	Deck Alarm	0	1.301	A	2
D4	Maretron	SIM100	1.0	1429902	2	1.1.1	1.2.2.2	Smoke Detectors	0	1.210	A	2
08	Maretron	IPG100	1.0	1620002	1	3.6.0	4.0.7.6	Secondary Ship's ...	1	1.301	A	3
A3	Maretron	J2K100	1.0	1241755	0	1.0.13.2	1.2.1.1	Main Ships HVAC	0	1.301	A	3
28	Maretron	VDR100	1.0	1760014	0	2.0.0.4	3.0.3.1	Primary Data Recorder	0	2.000	A	4
04	Maretron	USB100	1.0	1160253	2	1.8.3	1.8.6.2	Connected to Nav...	2	1.210	A	3
94	Maretron	EMS100	2.0	1220251	0	1.4.2.4	1.4.3.1	Engine Main	0	1.210	A	1
8D	Maretron	NBE100	1.0	1240263	0	1.0.0	1.1.0.1	Fwd Ship's NMEA200...	0	1.301	A	3
88	Maretron	DSM150	1.0	1800001	0	1.4.17.5	1.6.6.3	Captain's Quarters	0	2.000	A	3
78	Maretron	SMS100	1.0	1739904	0	1.0.1.1	-		0	1.301	A	2
15	Maretron	DSM250	2.0	1340328	2	1.4.14.4	1.6.6.3	Engine Room	2	1.301	A	13
14	Maretron	DSM250	3.0	1329901	4	1.4.16.5	1.6.6.3	Crew Quarters	4	2.000	A	13
D1	Maretron	RIM100	1.0	1459902	1	1.1.3	1.2.2.2	Fire Suppression Syst...	19	1.301	A	1
C3	Maretron	NBE100	1.0	1240360	0	1.0.0	1.1.0.1	Aft Ship's NMEA2000 ...	0	1.301	A	3
80	Maretron	DSM250	1.0	1309906	3	1.4.17.5	1.6.6.3	Fly_Bridge	3	2.000	A	13
70	Maretron	TLM100	1.0	1501234	0	1.1.6	1.1.8.3	Bow Holding Tank	0	1.301	B	2
6A	Maretron	FFM100	1.0	1679904	0	1.1.2.1	1.2.2.1	Main Engine	0	1.301	A	2
40	Maretron	DCP100	2.0	1700032	0	1.1.1.4	1.1.2.3	Lighting Control	0	2.000	A	3

5. Changing the DeviceInstance from the CCGX command line

Instead of using Actisense or Maretron software, it is also possible to change the device instance from the Color Control shell. To get root access, follow these instructions: [Venus OS: Root Access](#)

Once logged into the shell, follow below instructions. Note that the example shown changes the device instance of a Skylla-i. The device instance of a VE.Can connected MultiPlus or Quattro can be changed as well. It will show as `com.victronenergy.vebus.socketcan_can0_di0_xxxx`.

Step 1. List the devices:

```
root@ccgx:~# dbus -y
com.victronenergy.bms.socketcan_can0_di0_uc10
com.victronenergy.charger.socketcan_can0_di1_uc12983
```

It shows a Skylla-i (the charger). di1 in the name means that it is currently on DeviceInstance 1.

Step 2. Change it, for example, to 4:

```
root@ccgx:~# dbus -y com.victronenergy.charger.socketcan_can0_di0_uc12983
/DeviceInstance SetValue %4
retval = 0
```

Step 3. Wait a few seconds, and double check:

```
root@ccgx:~# dbus -y
com.victronenergy.bms.socketcan_can0_di0_uc10
com.victronenergy.charger.socketcan_can0_di4_uc12983
```

Device instance changed successful!

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