

# CCGX Hardware and software introduction

## Hardware

The CCGX is based on the Technexion board TAM-3517, which is using the Texas Instruments Sitara AM3517, containing a ARM Cortex-A8 microprocessor:



## Software

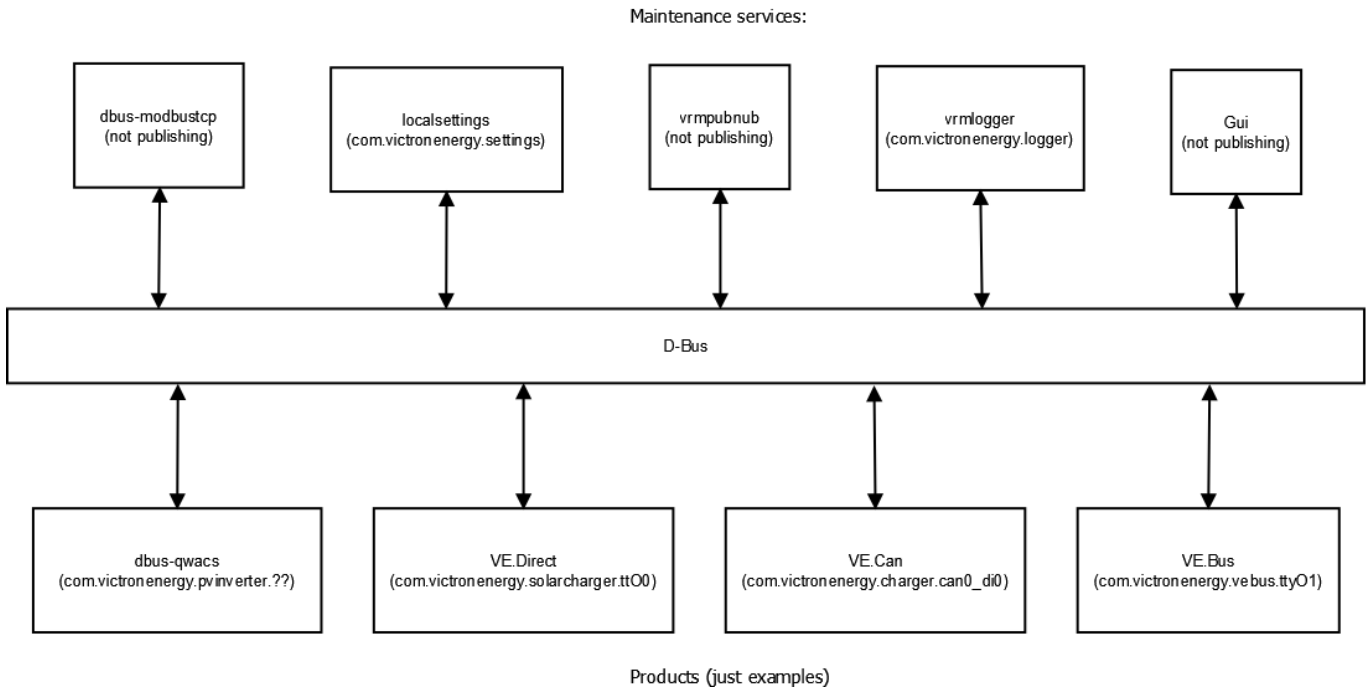
### Linux kernel & OS

The software platform of the CCGX is called Venus: Victron Energy Unix like distro with a linux kernel. It is based on and built with OpenEmbedded, a build framework for embedded Linux. It has all kinds of tools, mechanisms and recipes to build the Linux kernel and make a full embedded Linux rootfs. Maintained versions are listed here: <https://wiki.yoctoproject.org/wiki/Releases>.

To build the Venus yourself, see: <https://github.com/victronenergy/venus>

### Victron software

we are using a mixture of C, C++, QML (for the user interface) and Python. As a main data exchange, to share values such as voltages, as well as settings and other data, we use D-Bus. D-bus is for inter process communication, see google and the [D-Bus page on wikipedia](#) for more information. This diagram gives a good overview of the whole thing:



### Product processes

Processes that interface to products, using the different protocols. These processes make the information available on the D-Bus.

- VE.Can to dbus  
written in C, reads and writes to the VE.Can comm. port.
- mk2dbus  
written in C, reads and write to VE.Bus (Victron inverter/charger protocol).
- VE.Direct to D-Bus  
written in C, reads/writes to serial connected devices, such as the BMV and MPPT solar chargers.
- gps\_dbus  
also written in C. Open source: [https://github.com/victronenergy/dbus\\_gps](https://github.com/victronenergy/dbus_gps).
- dbus\_qwacs  
C++, using the QT library. Reads data from wireless AC sensors connected via an Ethernet-DECT gateway. Open source: [https://github.com/victronenergy/dbus\\_qwacs](https://github.com/victronenergy/dbus_qwacs)
- dbus-fronius  
written in C++, communications to Fronius PV inverters via LAN/Ethernet. Open source: <https://github.com/victronenergy/dbus-fronius>
- dbus-motordrive  
[https://bitbucket.org/oceanvolt/dbus\\_motordrive](https://bitbucket.org/oceanvolt/dbus_motordrive)

### Other processes

- gui  
Written in C++ and QML, uses QT. Takes care of the user interface: buttons and the display
- vrmlogger  
Written in Python, takes data from the dbus and submits it to the VRM Portal.  
<https://vrm.victronenergy.com/>
- localsettings

Written in Python, takes care of user settings. All other processes read and write their settings through this daemon via D-Bus. The daemon is an interface between D-Bus and the file `/data/conf/settings.xml`. Open source: <https://github.com/victronenergy/localsettings>.

- `dbus_modbustcp`

Written in C++, uses QT. Modbustcp server that can be used to access data of all products connected to the CCGX. See our [Data communication whitepaper](#) for more information. Open source: [https://github.com/victronenergy/dbus\\_modbustcp](https://github.com/victronenergy/dbus_modbustcp)

- `dbus-systemcalc-py`

Written in Python, publish PV totals and other system readings on D-Bus. The overviews on the CCGX get their information from this service (`com.victronenergy.system`). Open source: <https://github.com/victronenergy/dbus-systemcalc-py>

## Source code

As visible in above project list, part of the sources is already available. All that is open source is available on <https://github.com/victronenergy/>. The rest is still on Victrons internal git servers, and where possible slowly being moved to github.

## Other tips

- to make a screenshot, first press and hold the down button, and then press the up button. The screenshot will be saved with the name `snapshot.png` in `/opt/color-control/gui/` or `/service/gui`. Making a new screenshot overwrites the previous one.

And see [color\\_control\\_gx](#) for more CCGX development information

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