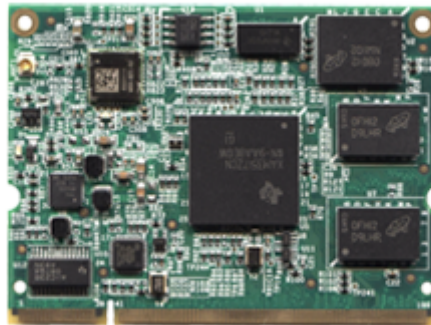# CCGX Hardware and software introduction

Hardware

The CCGX is based on the Technexion board TAM-3517, which is using the Texas Instruments Sitara AM3517, containing a ARM Cortex-A8 microprocessor:
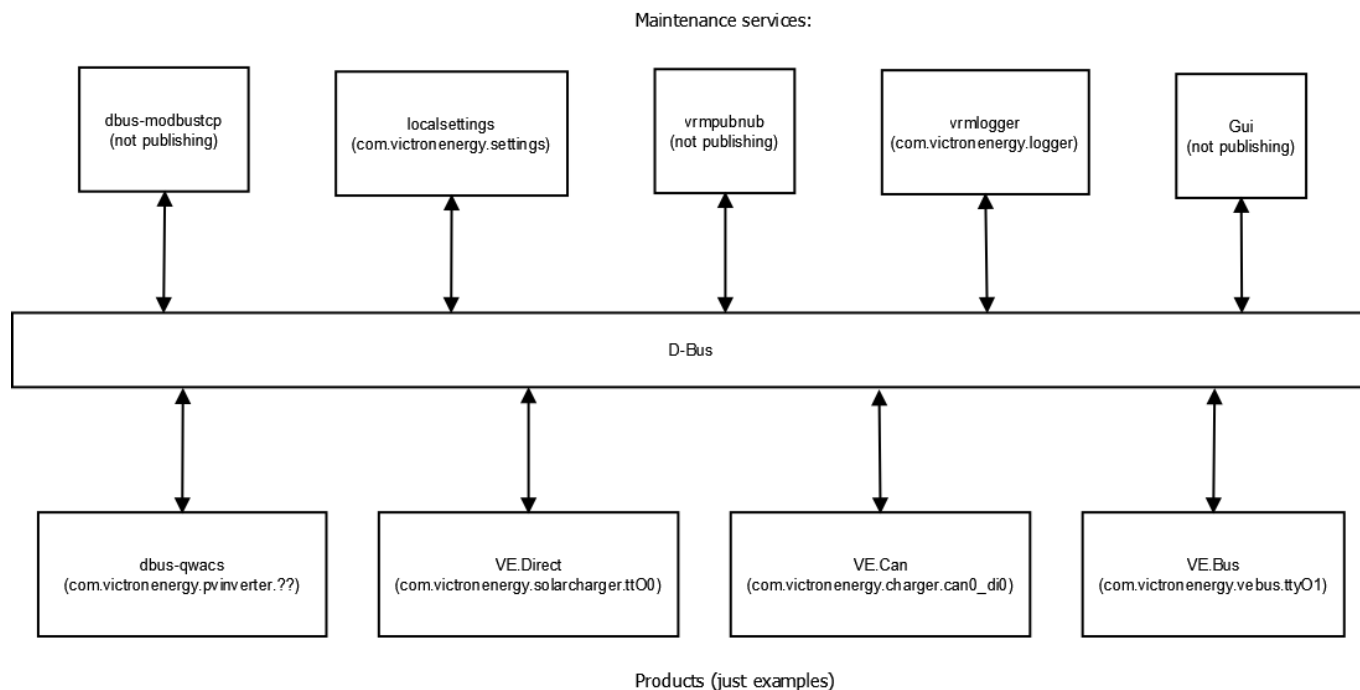

Software

Linux kernel & OS

The software platform of the CCGX is called Venus: Victron Energy Unix like distro with a linux kernel. It is based on and built with OpenEmbedded, a build framework for embedded Linux. It has all kinds of tools, mechanisms and recipes to build the Linux kernel and make a full embedded Linux rootfs. Maintained versions are listed here: https://wiki.yoctoproject.org/wiki/Releases.

To build the Venus yourself, see: https://github.com/victronenergy/venus

Victron software

we are using a mixture of C, C++, QML (for the user interface) and Python. As a main data exchange, to share values such as voltages, as well as settings and other data, we use D-Bus. D-bus is for inter process communication, see google and the D-Bus page on wikipedia for more information. This diagram gives a good overview of the whole thing:

Maintenance services:

dbus-modbustcp (not publishing)	localsettings (com.victronenergy.settings)	vrmpubnub (not publishing)	vrmlogger (com.victronenergy.logger)	Gui (not publishing)

D-Bus

dbus-qwacs (com.victronenergy.pvinverter.??)	VE.Direct (com.victronenergy.solarcharger.ttO0)	VE.Can (com.victronenergy.charger.can0_di0)	VE.Bus (com.victronenergy.vebus.ttyO1)

Products (just examples)

Product processes

Processes that interface to products, using the different protocols. These processes make the information available on the D-Bus.

- VE.Can to dbus
  written in C, reads and writes to the VE.Can comm. port.
- mk2dbus
  written in C, reads and write to VE.Bus (Victron inverter/charger protocol).
- VE.Direct to D-Bus
  written in C, reads/writes to serial connected devices, such as the BMV and MPPT solar chargers.
- gps_dbus
  also written in C. Open source: https://github.com/victronenergy/dbus_gps.
- dbus_qwacs
  C++, using the QT library. Reads data from wireless AC sensors connected via an Ethernet-DECT gateway. Open source: https://github.com/victronenergy/dbus_qwacs
- dbus-fronius
  written in C++, communications to Fronius PV inverters via LAN/Ethernet. Open source: https://github.com/victronenergy/dbus-fronius
- dbus-motordrive
  https://bitbucket.org/oceanvolt/dbus_motordrive

Other processes

- gui
  Written in C++ and QML, uses QT. Takes care of the user interface: buttons and the display
- vrmlogger
  Written in Python, takes data from the dbus and submits it to the VRM Portal.
  https://vrm.victronenergy.com/
- localsettings

Written in Python, takes care of user settings. All other processes read and write their settings through this daemon via D-Bus. The daemon is an interface between D-Bus and the file /data/conf/settings.xml. Open source: https://github.com/victronenergy/localsettings.

- dbus_modbustcp
Written in C++, uses QT. Modbustcp server that can be used to access data of all products connected to the CCGX. See our Data communication whitepaper for more information. Open source: https://github.com/victronenergy/dbus_modbustcp
- dbus-systemcalc-py
Written in Python, publish PV totals and other system readings on D-Bus. The overviews on the CCGX get their information from this service (com.victronenergy.system). Open source: https://github.com/victronenergy/dbus-systemcalc-py

Source code

As visible in above project list, part of the sources is already available. All that is open source is available on https://github.com/victronenergy/. The rest is still on Victrons internal git servers, and where possible slowly being moved to github.

Other tips

- to make a screenshot, first press and hold the down button, and then press the up button. The screenshot will be saved with the name snapshot.png in /opt/color-control/gui/ or /service/gui. Making a new screenshot overwrites the previous one.

DISQUS

~~DISQUS~~

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