

Venus command-line manual

1. Introduction

This page explains how to change settings and/or update firmware for various Victron products which are connected to a Venus device, for example the Color Control GX.

For more software developer oriented command line tips & tricks, see [here](#) on the Venus wiki.

Note regarding support: below documentation are made available to be convenient only. There is no guaranteed support on this type of using out products.

1.1 Use a normal tool instead of the command line

It is not at all necessary to use below command line instructions. We have far easier to use normal computer applications available:

VE.Bus products (Inverters, Multis, Quattros)

Changing settings with products featuring a VE.Bus comm. port (Inverters, Multis and Quattros) is normally done with VEConfigure.

Firmware updates are normally done with VEFirmware, a computer tool that is installed together with VEConfigure.

To change settings remotely, use [Remote VEConfigure](#).

Remotely updating firmware of a VE.Bus product is only possible from the command line, see below.

VE.Can products (Skylia-i, MPPT Solar Charger 150/75 & 150/85, and other products)

Updating VE.Can connected products is done with VE Power Setup, see [VE Power Setup manual](#). Both for a local update, as for a remote update via the internet.

Changing settings of a VE.Can connected product (except for the Lynx Shunt VE.Can, which can be altered on the Venus GUI, and of course then also via the d-bus from the command-line). Normally done on the LCD panel of the product itself.

VE.Direct products (MPPTs, BMV, Phoenix Inverter VE.Direct, and other products)

Both firmware updating as well as changing settings is normally done with [VictronConnect](#).

It is not possible to remotely change settings. Neither from the command line.

Updating firmware remote is only possible from the command line, see below.

1.2 Connecting to the command line and file transfer

See the [ccgx root access page](#) for an explanation on how to connect to the command line.

Besides accessing the command line, you might also need to send files back and forth. Use the [Secure copy, or scp](#), for that.

2. Venus software updates

2.1 Checking current version

```
root@CCGX:~# cat /opt/color-control/version
v2.06
Color Control GX
201612090913
```

2.2 Updating Venus version (Venus v1.74 and before)

To trigger an update check, run

```
/opt/color-control/opkg-scripts/check-updates.sh
```

If there are new updates found, and if the GUI is running and automatic updates are enabled, the GUI will automatically initiate an update followed by a reboot. Otherwise, trigger the installation yourself with

```
/opt/color-control/opkg-scripts/do-updates.sh
```

To change the Update-to setting, use set-feed.sh.

2.3 Automatic updates (Venus v1.74 and before)

To check if the device is configured to automatically update, query /Settings/System/AutoUpdate

```
dbus -y com.victronenergy.settings /Settings/System/AutoUpdate GetValue
```

The response will be either:

Status	Meaning
0	Automatic updates are disabled
1	Automatic updates are enabled

To change the setting, simply do the following (replace # with either 0 or 1):

```
dbus -y com.victronenergy.settings /Settings/System/AutoUpdate SetValue #
```

3. VE.Bus products

3.1 Changing settings

Step 1. Reading the settings

To read the settings use:

```
/opt/color-control/mk2vsc -r -s  
dbus://com.victronenergy.vebus.tty01/Interfaces/Mk2/Tunnel
```

-s specifies the serial port to use. In the above example we use the DBus MK2 tunnel. This is available when the vecan-mk2 service is active, which it normally is. For a direct connection use -s /dev/tty01

Optionally -f can be used to specify a custom file name to write the settings to

The generated file (.rvsc or .rvms) can be opened and edited on a PC using [VE Configure](#)

Step 2. Modifying the settings

Transfer the file to a computer running Windows, and which has the [VEConfigure toolset](#) installed.

On that computer, open the file by double clicking it, make the modifications, and save the file again.

Then transfer the new file back onto the Venus device.

Step 3. Writing the new settings to the system

To write the settings use:

```
/opt/color-control/mk2vsc -w -s  
dbus://com.victronenergy.vebus.tty01/Interfaces/Mk2/Tunnel
```

3.2 Updating VE.Bus firmware

Requires Venus v2.00 or later.

Using the vbdup tool. This can update firmware of the following products:

- Multi versions 26xyyyy/27xyyyy (minimum originally installed firmware, yyy needs to be 2xx or higher)
- MK3

Updating other VE.Bus devices, such as the VE.Bus BMS and Digital Multi Control panels is not possible with vbdup.

Make sure that the Venus device (fe. CCGX), nor the routers or any other used communications equipment, is powered by the VE.Bus devices. If they are, you'll lose power and connection as soon as the update is started, resulting in a dead system.

The product that you want to update needs to have application firmware running: just bootloader is not enough. The update starts with requesting the hardware IDs (VE.Bus discovery) from the running application. Those hardware IDs are then used to address the VE.Bus devices once in bootloader mode. After the discovery, the hardware IDs are stored in a file. In case, for example because of a power loss, the update fails, vbdup will automatically use the hardware IDs stored in that file.

Read the console help before use:

```
root@beaglebone:~# vbdup --help
vbdup version 0.05
```

Vebus device firmware updater.

Supported products:

- MK3
- Multi versions 26xyyyy/27xyyyy
where yyy >= 2xx

WARNING:

Updating will reset any user defined settings to default!

If you want to keep your settings you must use VeConfigure, local or remote, to readout and save the settings.

After updating, you can use VeConfigure again to restore the settings.

Firmware updates currently do not work through the dbus tunnel. Please close the vecan-mk2 before using this feature

Note, When updating to Multi firmware version 4xx

Serial numbers were introduced with Multi firmware 4xx.

In VEFash the user is requested to enter the serial number manually.

This code has no user interaction. We do not know the update order when multiple Multi's are connected.

Therefore the serial number will be generated using the unique target ID

Serial number format = tid##### where ##.. is the hexadecimal representation of the unique target ID.

Existing serial numbers when updating within the 4xx range will remain unchanged

Usage:

VBDUP OPTIONS:

```
-f, --file  
    vff/vfd vebus device firmware file.
```

COMMON OPTIONS:

```
-h, --help  
    Print this help.
```

```
--log-before <count>  
    When set to non zero <count> number of log lines, which are  
    not enabled themselves, are nevertheless shown before an  
    log which is enabled. For example an error message will be  
    preceeded by <count> warning and info messages which occurred  
    before the error. Combined with -v also warning messages will  
    be preceeded by info messages
```

```
--log-after <count>  
    Like -log-before, but temporarily enables tracing of disabled messages  
    after a warning or error occurred.
```

```
-s, --serial  
    the serial port to use (default /dev/ttyS0).
```

```
-i, --use-host-io-lines  
    Use host processor I/O lines to control MK2/MK3 reset and VE.Bus standby.
```

```
-v --verbose  
    Enable log messages. Specifying multiple times increases verbosity.
```

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Prior to updating a Multi the vecan-mk2 service should be stopped:

```
svc -d /service/vecan-mk2
```

To update run:

```
vbdup -f 2610408.vff -vvv -s /dev/tty01
```

-vvv is not required and only included to output messages on the console in order to see the tool at work.

Start the vecan-mk2 up again by:

```
svc -u /service/vecan-mk2
```

4. VE.Can products

First simply run vup to see connected products, and then follow onscreen instructions. No need to

stop the canbus service, you can run an update, and when done, it will automatically recognize the updated product.

```
root@bpp3:~# vup
Querying devices
| NAD  | man | serial          | boot  | bmode| vup| vup#| id   |
description      | version |
| 0x20 | 358 | 0013122         | 1.02  | -    | +  | 0   | 100  | BMV
to NMEA2000 interface | 1.06   |
| 0x20 | 358 | 0013122         | 1.02  | -    | -  | 1   | x    | x
| x      |
| 0x24 | 358 | 0013463 HQ1227H7JSJ | 1.00  | -    | +  | 0   | 108  |
BlueSolar Charger MPPT 150/70 | 2.02  |
```

To update the first device in the above list, use the following command:

```
vup -n 0x20 -f new_firmware.vup
```

For other devices, change the address, as found in the first column (NAD). The name of the firmware file depends on the product. E.g. `skyllai_control_v1.10.vup` for updating a Skylla-i Control to version 1.10.

4.2 Restoring VE.Can products to their defaults

WARNING: for chargers etc this is a bad idea to do remotely if you are not sure what you are doing, since charge voltages etc might be reset as well. It needs a ccgx version ≥ 1.30 . -n is address, the same as for vup, see above (and just type vup to get it).

```
vreg -n 0x24 -s 4
```

4.3 Restarting a VE.Can device

A bit of a trick: below code first sets them to bootloader mode, and then back out of it:

```
root@ccgx:~# vup -n 0x24 -u
Querying devices
Found device, enabling UDF.
UDF is ready to accept update.
Udf enabled, update can begin.

root@ccgx:~# vup -n 0x24 -e
Querying devices
Update end send
```

5. VE.Direct products

First make sure to stop the serial starter:

```
svc -d /service/serial-starter
```

List all services running:

```
svstat /service/*
```

Look for the product you and to update, and stop that service as well:

```
svc -d /service/vedirect.tty02 (for example)
```

Then update the product:

```
root@bpp3:~# dup -s /dev/tty02 -f filename.dup
VE.Direct Updater
Updating device on /dev/tty02
Locating device
Found BlueSolar Charger MPPT 75/15 (A042)
Retrieving calibration data
Found application v1.14
Entering bootmode
Found bootloader v1.01
Erasing device
Programming
Starting new firmware
Verifying new version
Found bootloader v1.01
Update successful
Restoring calibration data

root@bpp3:~#
```

and when done, start the service and the serial-starter again:

```
svc -u /service/vedirect.tty02
svc -u /service/serial-starter
```

6. Screenshot

To make a screenshot press and hold the upbutton, and then press the down button. You'll then find `/opt/color-control/gui/snapshot.png`

7. Enabling Remote Console

If you have a CCGX already installed, but Remote Console on VRM is not enabled, follow these steps to enable it remotely:

1. SSH into CCGX (make a root password by following instructions [here](#))

1. `dbus -y com.victronenergy.settings /Settings/System/VncInternet SetValue 1`

2. `dbus -y com.victronenergy.settings /Settings/System/VncLocal SetValue 1`

3. `touch /data/conf/vncpassword.txt`

2. Reboot CCGX via SSH:

```
reboot
```

3. Now you should be able to access Remote Console feature from VRM
4. If you want to set a password, go to Settings → Remote Console → Enable password check

8. Enabling VRM two-way communication (Remote VEConfigure aka vrmpubnub)

If you have a CCGX already installed, but VRM two-way communication is not enabled, follow these steps to enable it remotely:

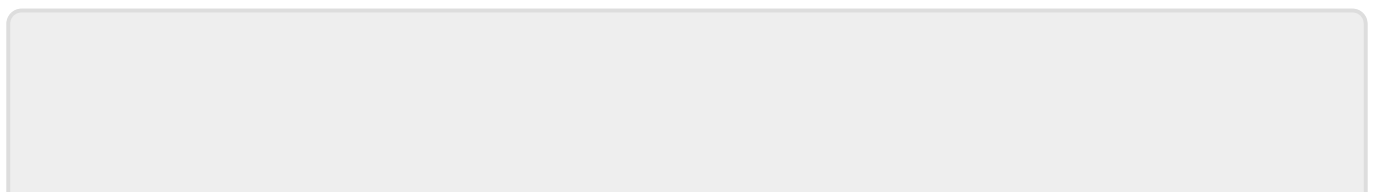
1. SSH into CCGX (make a root password by following instructions [here](#))

1. `dbus -y com.victronenergy.settings /Settings/Services/Vrmpubnub SetValue 1`

2. VE.Configure should now be able to connect to the CCGX

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